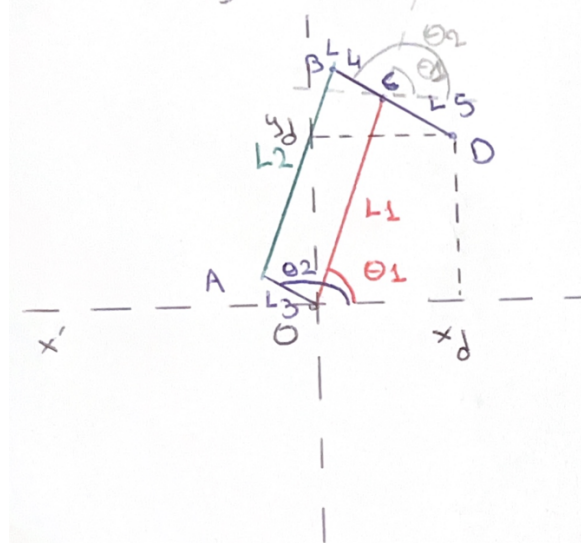
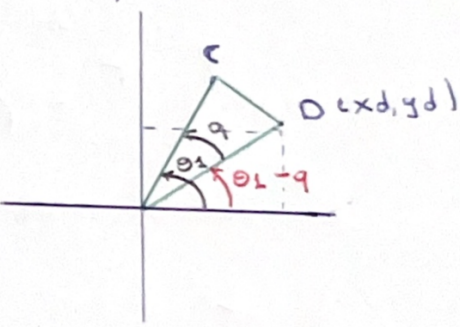


We know that $L1 = L2$ and $L3 = L4$, as well as $L1 \parallel L2$ and $L3 \parallel L4$. θ_1 and θ_2 can rotate around O $(0,0)$ independently while respecting the following condition $0 \leq \theta_1 + \theta_2 \leq 180$. We are searching to express x_d and y_d in relation with $L1$, $L2$, θ_1 , θ_2 , etc.



| Step | Analysis |
|------|--|
| | $\theta_2 = \arctan\left(\frac{y_a}{x_a}\right)$ <p>car</p> $\tan(\theta) = \frac{y}{x}$ |
| | $\theta_1 = \arctan\left(\frac{y_c}{x_c}\right)$ |
| | <p>From cosinus lema we have:</p> $p^2 = L1^2 + L5^2 - 2 L1 L2 \cos(\theta_2 - \theta_1)$ <p>so</p> $p = \sqrt{L1^2 + L5^2 - 2 L1 L2 \cos(\theta_2 - \theta_1)}$ <p>and from sinus lema we have:</p> $\frac{\sin(q)}{L5} = \frac{\sin(\theta_2 - \theta_1)}{p} \Leftrightarrow \sin(q) = \frac{L5}{p} \sin(\theta_2 - \theta_1)$ |

| | |
|---|---|
|  | $x_d = p \cos(\theta_1 - q)$ $y_d = p \sin(\theta_1 - q)$ |
|---|---|

so by replacing q and p from previous step we take:

$$x_d = \sqrt{L_1^2 + L_5^2 - 2 L_1 L_2 \cos(\theta_2 - \theta_1)} \cos(\theta_1 - \arcsin(\frac{L_5}{\sqrt{L_1^2 + L_5^2 - 2 L_1 L_2 \cos(\theta_2 - \theta_1)}}) \sin(\theta_2 - \theta_1))$$

and

$$y_d = \sqrt{L_1^2 + L_5^2 - 2 L_1 L_2 \cos(\theta_2 - \theta_1)} \sin(\theta_1 - \arcsin(\frac{L_5}{\sqrt{L_1^2 + L_5^2 - 2 L_1 L_2 \cos(\theta_2 - \theta_1)}}) \sin(\theta_2 - \theta_1))$$